A geometric perspective on duality symmetries in supergravity

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Based on $\underline{2311.12095}$ with
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## Introduction

## Dualities in string \& M-theory

11d SUGRA

$$
\begin{align*}
S_{\mathrm{eff}}^{(d=11)}= & \frac{1}{2 \kappa_{11}^{2}}\left[\int d^{11} x \sqrt{-G}\left(R-\frac{1}{2 \cdot 4!} F_{M_{1} \ldots M_{4}} F^{M_{1} \ldots M_{4}}\right)\right. \\
& \left.-\frac{1}{6} \int A_{3} \wedge F_{4} \wedge F_{4}\right] \tag{16.131}
\end{align*}
$$

## Dualities in string \& M-theory



## Dualities in string \& M-theory




Het. $E_{8} \times \mathrm{E}_{8}$
Type IIA

$$
S_{\mathrm{IIA}}=\frac{1}{2 \tilde{\kappa}_{10}^{2}} \int d^{10} x \sqrt{-G}\left[e^{-2 \Phi}\left(R+4(\nabla \Phi)^{2}-\frac{1}{2}\left|H_{3}\right|^{2}\right)-\frac{1}{2}\left|F_{2}\right|^{2}-\frac{1}{2}\left|F_{4}\right|^{2}\right]
$$

$$
-\frac{1}{4 \tilde{\kappa}_{10}^{2}} \int B_{2} \wedge d C_{3} \wedge d C_{3},
$$

$$
(16.134 a)
$$

$$
S_{\mathrm{IIB}}=\frac{1}{2 \tilde{\kappa}_{10}^{2}} \int d^{10} x \sqrt{-G}\left[e^{-2 \Phi}\left(R+4(\nabla \Phi)^{2}-\frac{1}{2}\left|H_{3}\right|^{2}\right)-\frac{1}{2}\left|F_{1}\right|^{2}-\frac{1}{2}\left|F_{3}\right|^{2}\right.
$$

$$
\begin{equation*}
\left.-\frac{1}{4}\left|F_{5}\right|^{2}\right]-\frac{1}{4 \tilde{\kappa}_{10}^{2}} \int C_{4} \wedge H_{3} \wedge F_{3} \tag{16.134b}
\end{equation*}
$$

Het. SO(32)
Type IIB


$$
S_{\mathrm{I}}=\frac{1}{2 \tilde{\kappa}_{10}^{2}} \int d^{10} x \sqrt{-G} e^{-2 \Phi}\left(R+4(\nabla \Phi)^{2}-\frac{1}{2}\left|H_{3}\right|^{2}\right)
$$

Type $\left\lvert\, \quad-\frac{1}{2 \tilde{g}_{10}^{2}} \int d^{10} x \sqrt{-G} e^{-2 \Phi} \operatorname{Tr}\left(\left|F_{\mathrm{YM}}\right|^{2}\right)\right.$,

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$$

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- split spacetime into $11=\mathrm{n}+\mathrm{d}$
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- i.e. $\mathrm{d}=4$ with U -duality group $\mathrm{SL}(5)$ and the multiplets
generalized

metric $\underset{\text { Scalars }}{\text { Metric }} \quad$| $\mathcal{M}_{M N} \in \frac{\mathrm{SL}(5)}{\mathrm{SO}(5)}$ | $g_{i j}(10)$ | $C_{i j k}(4)$ |  |
| :---: | :---: | :---: | :---: |
| One-forms | $\mathcal{A}_{\mu} \in \mathbf{1 0}$ | $A_{\mu}{ }^{i}(4)$ | $C_{\mu i j}(6)$ |
| Two-forms | $\mathcal{B}_{\mu \nu} \in \overline{\mathbf{5}}$ | $C_{\mu \nu i}(4)$ | $C_{\mu \nu i j k l}(1)$ |
| Three-forms | $\mathcal{C}_{\mu \nu \rho} \in \mathbf{5}$ | $C_{\mu \nu \rho}(1)$ | $C_{\mu \nu \rho i j k}(4)$ |
| Four-forms | $\mathcal{D}_{\mu \nu \rho \sigma} \in \overline{\mathbf{1 0}}$ | $C_{\mu \nu \rho \sigma i j}(6)$ | $\tilde{A}_{\mu \nu \rho \sigma i}(4)$ |

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| $d$ |  | $E_{d(d)}$ |  |
| :---: | :---: | :---: | :---: |
| 2 | 0 | 0 | $\mathrm{SL}(2) \times \mathbb{R}^{+}$ |
| 3 | $0-0$ | $\mathrm{SL}(3) \times \mathrm{SL}(2)$ |  |
| 4 | $0-0-0$ | $\mathrm{SL}(5)$ |  |
| 5 | $0-0-0$ | $\mathrm{SO}(5,5)$ |  |
| 6 | $0-0-0-0$ | $E_{6(6)}$ |  |
| 7 | $0-0-0-0-0$ | $E_{7(7)}$ |  |
| 8 | o-0-0-0-0-0-0 | $E_{8(8)}$ |  |

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| $\underset{\text { metric }}{\text { generalized }} \xrightarrow[\text { Scalars }]{\text { Metric }}$ | $\begin{gathered} g_{\mu \nu} \\ \mathcal{M}_{M N} \in \frac{\mathrm{SL}(5)}{\mathrm{SO}(5)} \end{gathered}$ | $g_{i j}(10)$ | $C_{i j k}$ (4) |
| :---: | :---: | :---: | :---: |
| One-forms | $\mathcal{A}_{\mu} \in 10$ | $A_{\mu}{ }^{i}$ (4) | $C_{\mu i j}$ (6) |
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| Three-forms | $\mathcal{C}_{\mu \nu \rho} \in 5$ | $C_{\mu \nu \rho}$ (1) | $C_{\mu \nu \rho i j k}$ (4) |
| Four-forms | $\mathcal{D}_{\mu \nu \rho \sigma} \in \overline{\mathbf{1 0}}^{\text {¢ }}$ | $C_{\mu \nu \rho \sigma i j}$ (6) | $\tilde{A}_{\mu \nu \rho \sigma i}$ (4) |


| $d$ |  | $E_{d(d)}$ |
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| 2 |  | $\mathrm{SL}(2) \times \mathbb{R}^{+}$ |
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## Manifest U-duality: Symmetries

generalized metric: $\mathcal{M}_{M N}=E^{A}{ }_{M} E^{B}{ }_{N} \mathcal{M}_{A B}, \quad E^{A}{ }_{M} \in \mathrm{SL}(5)$

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generalized frame with $\quad \delta E^{A}{ }_{M}=\mathbb{L}_{\xi} E^{A}{ }_{M}+\Lambda^{A}{ }_{B} E^{B}{ }_{M}, \Lambda^{A}{ }_{B} \in \operatorname{SO}(5)$

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$\underline{\text { generalized Lie derivative }}$

1) diffeomorphisms (gravity)
2) gauge tranformation
generalized Lorentz transformation
transformation of fermions

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## Manifest U-duality: geometry

We have a Lie derivative... What about parallel transport?

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## Covariant derivative:

$$
\nabla_{A} E_{B}^{M}=E_{A}^{N} \partial_{N} E_{B}{ }^{M}+\Omega_{A B}{ }^{C} E_{C}{ }^{M}-E_{A}{ }^{N} \Gamma_{N L}{ }^{M} E_{B}{ }^{L}
$$

*) $E_{A}{ }^{M} E^{B}{ }_{M}=\delta_{A}{ }^{B}$

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$$

Curvature and torsion???:

$$
\left[\nabla_{A}, \nabla_{B}\right] V^{C}=R_{A B D}{ }^{C} V^{D}+T_{A B}{ }^{D} \nabla_{D} V^{C}
$$

## A partial fix

- torsion can be quite easily defined:

$$
T_{A B}^{C} E_{C}:=\mathbb{L}_{E_{A}}^{\nabla} E_{B}-\mathbb{L}_{E_{A}} E_{B}
$$

$$
\left.{ }^{*}\right) \mathrm{L}_{U} V^{M}=U^{N} \partial_{N} V^{M}-\alpha P_{(\operatorname{adj})}{ }^{M}{ }_{N,}{ }^{P}{ }_{Q} \partial_{P} U^{Q} V^{N}+\beta \partial_{N} U^{N} V^{M}
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- only few covariant projections known, not the full Riemann tensor, i.e.

$$
S_{\text {eff }}=\cdots+\int \mathrm{d}^{n} x \mathrm{~d}^{d} y \sqrt{g} R \quad \swarrow \begin{aligned}
& \text { gen. } \\
& \text { curvature } \\
& \text { scalar }
\end{aligned}
$$

$\mathrm{E}_{11(11)} \begin{gathered}\text { gen. Einstein-Hilbert } \\ \text { action }\end{gathered}$
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Exceptional Generalized Geometry

* 2007
or
Exceptional Field
Theory
* 2012
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Generalized
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A hierarchy of curvatures

## A better solution

The problem: find covariant curvature under gen. Lorentz tr.
gen. diffeomorphisms
gen. structure group F tr.

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The problem: find covariant curvature under gen. Lorentz tr.

## gen. diffeomorphisms

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Observation: tensor hierarchy combines

In three words: symmetries for symmetries

diffeomorphisms (external)


8
gen. diffeomorphisms (internal)

## A better solution

The problem: find covariant curvature under gen. Lorentz tr.

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Observation: tensor hierarchy combines

In three words: symmetries for symmetries

diffeomorphisms (external)

gen. diffeomorphisms (internal)

Ne-purpose the tensor hierarchy to construct covariant curvature tensorS

## Tensor hierarchy 101

- different approaches, best for our purpose is level decomposition

$$
\mathrm{E}_{p(p)} \rightarrow \underset{\substack{\text { gen. diffs }}}{\mathrm{E}_{d(d)} \times \mathrm{GL}(m), \quad p=d+m} \text { contains gen. structure group } F \subset \mathrm{GL}(m), m=\operatorname{dim}(F)
$$

## Tensor hierarchy 101

- different approaches, best for our purpose is level decomposition

bexa1 1 teat.1 The next level
$\left[\widetilde{R}_{A}^{\alpha}, R_{\beta}^{B}\right]=\delta_{A}^{B}\left(\beta \delta_{\alpha}^{\beta} L-K_{\beta}^{\alpha}\right)+\alpha \delta_{\beta}^{\alpha}\left(t^{\mathbf{a}}{ }_{A}^{B} K_{\mathbf{a}}\right.$
$R_{1}$ representation of the duality group

$$
\left[\widetilde{R}_{A}^{\alpha}, R_{\beta}^{B}\right]=\delta_{A}^{B}\left(\beta \delta_{\alpha}^{\beta} L-K_{\beta}^{\alpha}\right)+\alpha \delta_{\beta}^{\alpha}\left(t^{\mathbf{a}}\right)_{A}^{B} K_{\mathbf{a}}
$$

$R_{1}$ representation of the duality group

$$
\left[R_{\alpha}^{A}, R_{\beta}^{B}\right]=\eta^{A B \bar{C}} R_{\alpha \beta \bar{C}} \leftarrow R_{2} \text { representation }
$$

${ }^{\text {neex 1 }} \quad$ leap. 1 The next level

$$
\left[\widetilde{R}_{A}^{\alpha}, R_{\beta}^{B}\right]=\delta_{A}^{B}\left(\beta \delta_{\alpha}^{\beta} L-K_{\beta}^{\alpha}\right)+\alpha \delta_{\beta}^{\alpha}\left(t_{\mu}^{\mathbf{a}}\right)_{A}^{B} K_{\mathbf{a}}
$$

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$$

|  | $\mathrm{O}(d, d)$ | $\mathrm{SL}(5)$ | $\operatorname{Spin}(5,5)$ | $\mathrm{E}_{6(6)}$ | $\mathrm{E}_{7(7)}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $\alpha$ | 2 | 3 | 4 | 6 | 12 |
| $\beta$ | 0 | $1 / 5$ | $1 / 4$ | $1 / 3$ | $1 / 2$ |
| $R_{1}$ | $\mathbf{2 d}$ | $\overline{\mathbf{1 0}}$ | $\mathbf{1 6}_{\mathrm{c}}$ | $\mathbf{2 7}$ | $\mathbf{5 6}$ |
| $R_{2}$ | $\mathbf{1}$ | 5 | $\mathbf{1 0}$ | $\overline{\mathbf{2 7}}$ | $\mathbf{1 3 3}$ |
| $R_{3}$ | - | 5 | $\mathbf{1 6}_{\mathrm{s}}$ | $\mathbf{7 8}$ | $\mathbf{9 1 2}$ |

All levels beyond $-1,0,1$ are completely fixed by the Jacobi identity.

## $E_{p(p)}$ generalized Lie derivative

- acts on the $R_{1}$ representation and its dual $\overline{R_{1}}$
on the megaspace
- built from the highest/lowest weight state



## $E_{p(p)}$ generalized Lie derivative

- acts on the $R_{1}$ representation and its dual $\overline{R_{1}}$


## on the megaspace

- built from the highest/lowest weight state

${ }^{*}$ ) index-free version of $\mathrm{L}_{U} V^{M}=U^{N} \partial_{N} V^{M}-\alpha P_{(\mathrm{adj})}{ }^{M}{ }_{N}{ }^{P}{ }_{Q} \partial_{P} U^{Q} V^{N}+\beta \partial_{N} U^{N} V^{M}$



## Megaspace torsion

gen. Lorentz tr.
covarint under gen. diff

gen. structure group F tr.
gen. torsion (twisted) for frame $\quad \widehat{E}=\widetilde{M} N \widetilde{V}$

$$
\left.X_{\mathcal{A}}=\left.\left\langle_{\mathcal{A}}\right| N\right|^{\mathcal{B}} \Theta_{\mathcal{B}}+\left.\left\langle_{\mathcal{A}}\right| \Theta_{\mathcal{B}} Z N\right|^{\mathcal{B}}\right\rangle
$$

## Megaspace torsion

gen. Lorentz tr.
\& gen. diffeomorphisms
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$$

$\mathrm{x}_{\mathcal{A}}=\left(\begin{array}{ll}X_{\alpha} & X_{A}\end{array}\right) \quad=\widetilde{M}^{-1} D_{\mathcal{A}} \widehat{E} \widehat{E}^{-1} \widetilde{M}$

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$$

$$
\begin{gathered}
\mathrm{x}_{\mathcal{A}}=\left(\begin{array}{ll}
X_{\alpha} & X_{A}
\end{array}\right) \quad=\widetilde{M}^{-1} D_{\mathcal{A}} \widehat{E} \widehat{E}^{-1} \widetilde{M} \\
\left.\widetilde{V}|\partial\rangle=\left.\right|^{\mathcal{A}}\right\rangle D_{\mathcal{A}}
\end{gathered}
$$

# Megaspace torsion 

covarint under gen. diff

$\cup$
gen. structure group F tr.
gen. torsion (twisted) for frame $\quad \widehat{E}=\widetilde{M} N \widetilde{V}$

$$
\begin{gathered}
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\mathrm{x}_{\mathcal{A}}=\left(\begin{array}{ll}
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\widetilde{V}|\partial\rangle=|\mathcal{A}\rangle D_{\mathcal{A}}
\end{gathered}
$$

torsion
\&

## curvatures

on the phyiscal space

## Exceptional Poláček-Siegel form <br> ...or how to fix the frame I

## Exceptional Poláček-Siegel form

 ...or how to fix the frame I$$
\begin{aligned}
& \widehat{E}=\widetilde{M} N \widetilde{V} \\
& \quad \swarrow \\
& \widetilde{M}^{-1} D_{\alpha} \widetilde{M}=t_{\alpha}
\end{aligned}
$$

$$
\text { generators of the structure group } F \subset \mathrm{GL}(m)
$$

## Exceptional Poláček-Siegel form

 ...or how to fix the frame I$$
\begin{aligned}
& \widehat{E}=\widetilde{M} N \widetilde{V} \\
& \widetilde{M}^{-1} D_{\alpha} \widetilde{M}=t_{\alpha} \quad \text { generators of the structure group } F \subset \mathrm{GL}(m) \\
& D_{\alpha} \widetilde{V} \widetilde{V}^{-1}=-\frac{1}{2}\left(X_{\alpha \beta}{ }^{\gamma}+\ldots\right) K_{\beta}^{\gamma} \quad \text { choosen such that } \\
& X_{\alpha}=t_{\alpha} \text { with }\left[t_{\alpha}, t_{\beta}\right]=X_{\alpha \beta}{ }^{\gamma} t_{\gamma}
\end{aligned}
$$

¿ Exceptional Poláček-Siegel form ...or how to fix the frame I

$$
\begin{aligned}
& \widehat{E}=\widetilde{M} N \widetilde{V} \\
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\end{aligned}
$$

## Exceptional Poláček-Siegel form

 ...or how to fix the frame I$$
\begin{aligned}
& \widehat{E}=\widetilde{M} N \widetilde{V} \\
& N=\exp \left(\Omega_{A}^{\alpha} R_{\alpha}^{A}+\frac{1}{2} \rho^{\alpha \beta \bar{C}} R_{\alpha \beta \bar{C}+\ldots}\right)
\end{aligned}
$$

## Exceptional Poláček-Siegel form

 ...or how to fix the frame I

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 ...or how to fix the frame I

## results in

$$
X_{A}=X_{A}^{\mathbf{b}} K_{\mathbf{b}}+X_{A B}^{\beta} R_{\beta}^{B}+\frac{1}{2} X_{A}^{\beta_{1} \beta_{2} \bar{B}} R_{\beta_{1} \beta_{2} \bar{B}}+\ldots
$$

## Possible Link?

## Cartan geometry...

## Symplectic reduction...


...unifies Torsion and curvature in a similar way.
...on the phase space of gauge theories has similar feature.

## Applications

## Dualities revisited

- Historical development of T-dualites

abelian<br>non-abelian<br>Poisson-Lie<br>WZW-Poisson

## Dualities revisited

- Historical development of T-dualites



## Dualities revisited

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generalized T-dualities
Applications:
- solution generating techniques
- consistent truncations
- integrable strings


## Underlying structure

Homogenious space:
A space that looks everywhere the same as you move through it.

$$
\text { isometry } \longleftrightarrow G / \boldsymbol{F} \longleftrightarrow \text { isotropy }
$$

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Homogenious space: A space that looks everywhere the same as you move through it.

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but in Generalized Geometry
with generalized Lie derivative: $\mathrm{L}_{U} V^{M}$
and section condition for closure


## Generalized group manifold

$\mathbb{L}_{E_{A}} E_{B}{ }^{M}=F_{A B}{ }^{C} E_{C}{ }^{M}$
gen. frame
structure constants

## Generalized group manifold

$$
\mathbb{L}_{E_{A}} E_{B}^{M}=F_{A B}^{C} E_{C}{ }^{M}<\text { structure constants } \text { gen. frame }
$$

$O(D, D)$ recipe to contruct gen. frame:

1) Lie algebra with generators $T_{A}$

$$
\left[T_{A}, T_{B}\right]=F_{A B}^{C} T_{C}
$$

2) with ad-invariant, $O(D, D)$-pairing

$$
\left\langle T_{A}, T_{B}\right\rangle=\eta_{A B}
$$

3) maximally isotropic subgroup

## Generalized group manifold

$$
\mathbb{L}_{E_{A}} E_{B}{ }^{M}=F_{A B}^{C} E_{C}{ }^{M} \Longleftarrow \text { gen. frame }
$$

$O(D, D)$ recipe to contruct gen. frame:


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Theorem: Let $(\mathrm{M}, \mathrm{g})$ be a connected and simply-connected complete Riemannian [Ambrose, Singer 1958] manifold. Then, the following statements are equivalent:

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frame and connection required

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\nabla_{i} e_{a}^{j}=\partial_{i} e_{a}^{j}-\omega_{i a}^{b} e_{b}^{j}+\Gamma_{i k}^{j} e_{a}^{k}=0
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## Generalized coset

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$\mathrm{O}(\mathrm{D}, \mathrm{D})$ recipe to contruct gen. frame and spin connection:

1) gen. frame on HIG = mega-space
2) another isotropic subgroup $F$

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$\mathrm{O}(\mathrm{D}, \mathrm{D})$ recipe to contruct gen. frame and spin connection:


$$
\begin{gathered}
E_{A}^{I} \text { and } \Omega_{I A}^{B} \\
\text { on double coset } \\
H \backslash G / F
\end{gathered}
$$

gen. structure group

- higher derivative connections from tensor hierarchy
- singularities @ fixed points of F action


## Summary and outlook

- finally covariant curvatures for execptional gen. geometry / field theory
- ulitmate goal is to use geometry, like in GR, to fix (as much as possible)

1) target space low-energy effective action
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